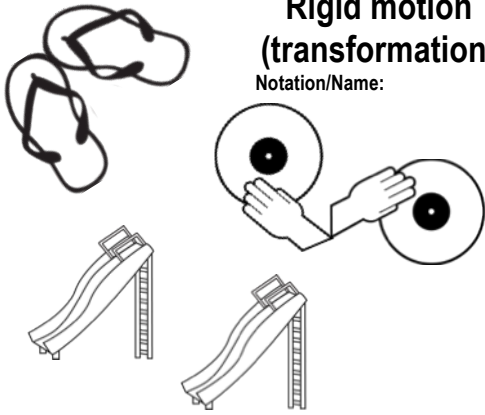


Diagram

Term

**Rigid motion
(transformation)**
Notation/Name:



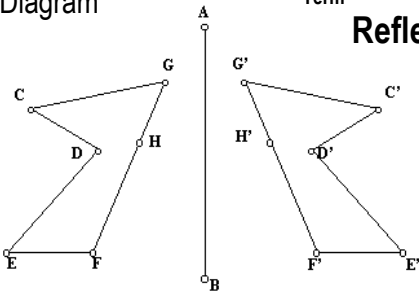
Description:

A transformation of the plane is a function that assigns to each point P of the plane a unique point $F(P)$ in the plane. Rigid motions are transformations that preserve _____ of segments and _____ of angles. A dilation is an example of a transformation that preserves _____ measures but not the lengths of segments. In this lesson, we will work only with rigid transformations. We call a figure that is about to undergo a transformation the _____ while the figure that results from the transformation is called the _____.

Diagram

Term

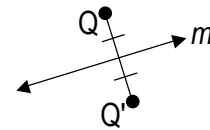
Reflection



Notation/Name:

Description:

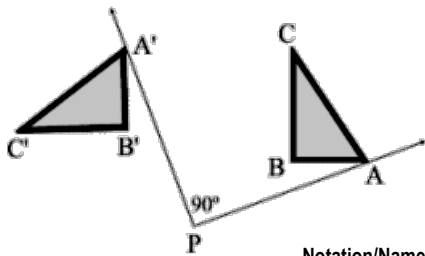
Reflections are rigid motion functions of the plane such that:
(a) Any point P on the line of the reflection maps to _____ ($P' = P$)
(b) Any point Q not on the line of reflection maps to Q' such that the line of reflection is the _____ of $\overline{QQ'}$. Notation: $r_m(Q)$ means reflect Q across line m .



Diagram

Term

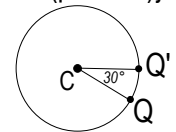
Rotation



Notation/Name:

Description:

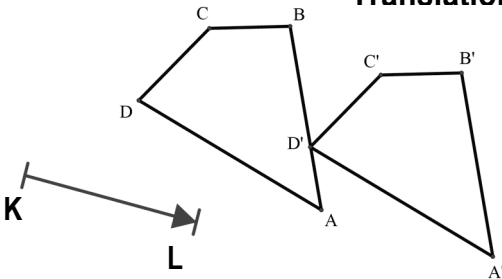
Reflections are rigid motion functions of the plane around a center point C such that:
(a) The center of rotation, point C , maps to _____ ($C' = C$)
(b) Any point Q that is not the center of rotation maps to a point Q' on _____ C with _____ CQ such that $m\angle QCQ'$ is equal to the degree of the rotation. {which includes direction --clockwise (negative) or counterclockwise (positive)}
Notation: $R_{C,30^\circ}(Q)$ means rotate point Q 30° counterclockwise around point C .



Diagram

Term

Translation



Notation/Name:

Description:

Translations are rigid motion functions of the plane along a vector (path) with distance and direction such that:
(a) any point P on the line containing the vector maps to a point P' on the line so that PP' has the same distance and direction as the given vector
(b) any point Q not on the line containing the vector maps to a point Q' so that QQ' is on a line parallel to the line containing the vector and QQ' is the length and direction of the given vector on a line parallel to the given vector.
Notation: $T_{\overline{AB}}(Q)$

